HCF
禾川 科技

AMD530B

l¬ nö l` '#A8 ^p

nöo³h#öA@ù.§

AMD CiA402 / /IO /

nöo³n÷WE a.ï

1.

2.

1

12PIN 1

1

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nöo³&øwZt4Ž

AMD ____ _ - _ D _ __ - _____

1 2 3 4 5 6

nöo³Cµù:”XD6¼

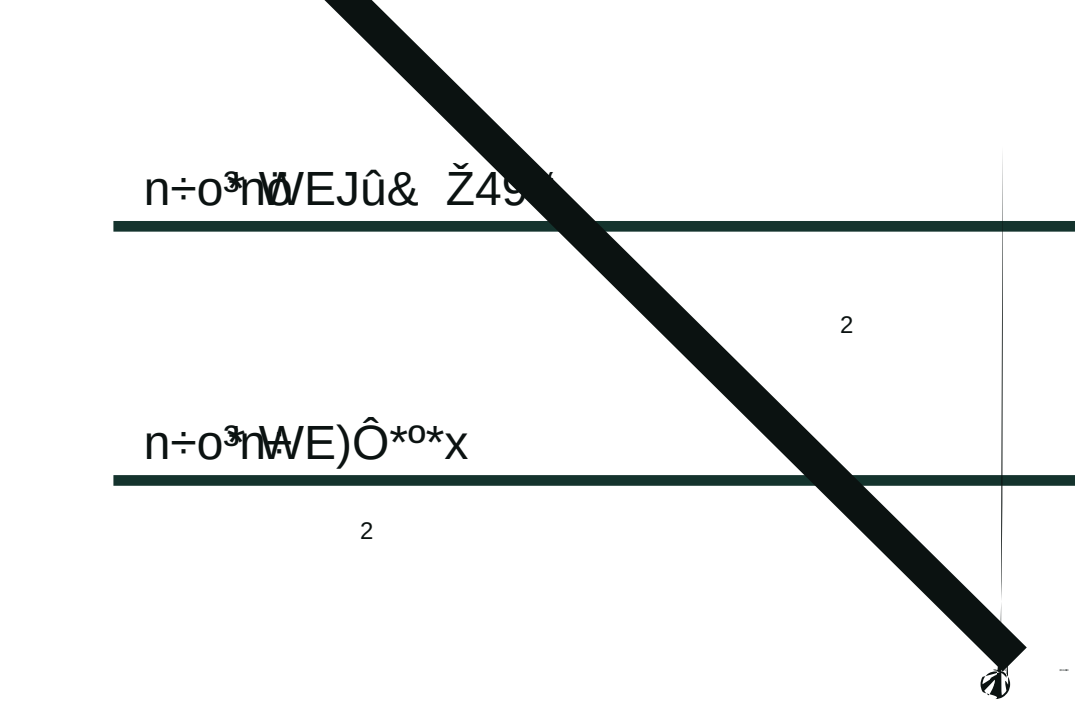
	AMD B- D	
)	1.0~8.1A	
	28~86	
	24~75Vdc	
L*W*H mm)	134*82*29	
	0.262kg	
	HCS_Studio.exe	

n÷o³nWEJû& Ž49

2

n÷o³nWE)Ô*o*x

2



Cµ5º6Æ66E 2%%°0–Cµ5ºE 2%%°

FG FG

^ å^ z a"wC¨CµM† - zB0$êfs4v

CµM†E %z*

( )

nøo³Cµø= # Cµ5ºIo)ÐE ^^2%

l¬ nù l` A ; \E n E =Zƒ ZU]ï v

PC (RS485) HCS_Studio.exe 2000

1. STEPPER

nûo²nø¶8¡-•E Z>*

6060h 6061h

1	Profle position mode	PP	
3	Profle velocity mode	PV	
6	Homing mode	HM	
8	Cyclic synchronous position mode	CSP	
9	Cyclic synchronous velocity mode	CSV	

nûo³N Ü8¡-• ‹E ñ"ŒZ>*

nûo³nù²•ñ)ö×p nûnõnùnõ p

6-2 (6040h)

7 3~0 402 6-3

6-3 7 3~0

							)
	0	×	1	1	0	0006h	2;6;8
	0	0	1	1	1	0007h	3*
	0	1	1	1	1	000Fh	3**
	0	×	×	0	×	0000h	7;9;10;12
	0	×	0	1	×	0002h	7;10;11
	0	0	1	1	1	0007h	5
	0	1	1	1	1	000Fh	4;16
		×	×	×	×	0080h	15

8 6~4 6-4

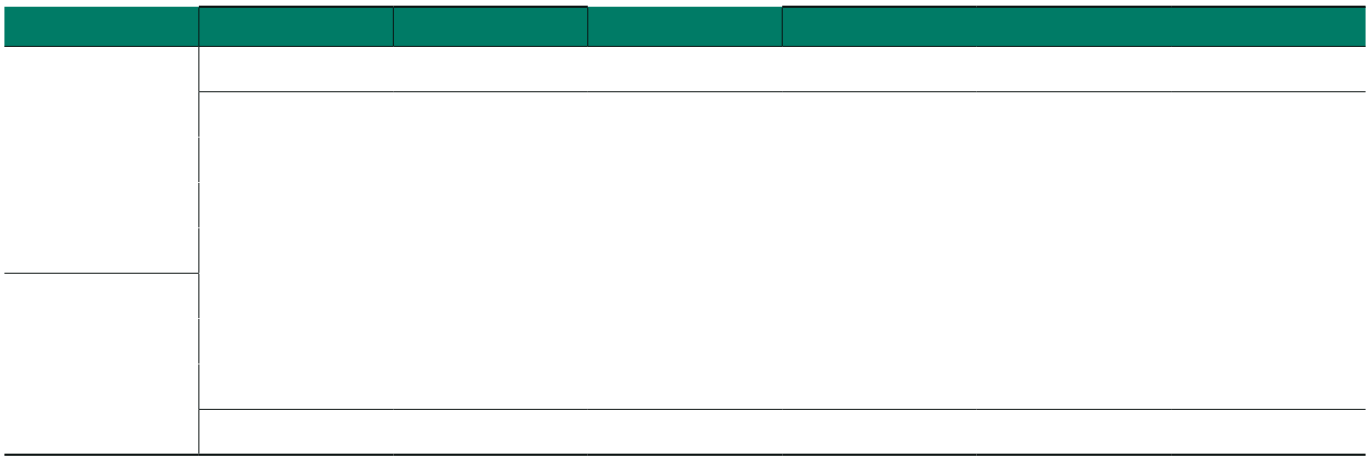
6-4 8 6~4

	(PP)	(Pç)	(CSç)	(HM)	(CSP)
8					
6	/				
5					
4					

p p Ex ó"B3ð

( )

6-6 PP



A

B ( )

C ( )

p p Ex ó"B3ð

( )

6-10 HM

nûo³nǖo³rÿ-&8¡-•

p €p!o³}2O^p

PV CSV PP CSP PV PV

PV (6041h) 15~12 10 8

6-16 PV 15~12 10 8

( )		
8( )	0	
	1	
10( )	0	
	1	
12(0)	0	0
	1	0 0 *1)

) Pç

—Pç

l¬ nü l` ,¸C¨! O}

DO

11		
12	2 0 2 1 2	
13	2 0 2 1 2	
14		2 0 DI5
15		2 DI 0 DI5 1 DI5

¾ (Õ ÿC¨2"c ! O}oä9åi$(‹oâ

1 DI

1 DI4 P02.03=5; 2 DI5 P02.04=6

P02.03	DI4 “5” 1
P02.04	

l¬ ný l` *yZá)× ø

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nýo³nyZá)× øMS6

CiA402

0x0000~0xFFFF	
0x1000~0x1FFF	COE
0x2000~0x5FFF	
0x6000~0x9FFF	

2000	0x1010-02	0x65766173	2000
	0x1010-02	0x74736572	
6000	0x1010-01	0x65766173	6000
	0x1010-01	0x74736572	

nýo³nyZáMDnõ ‘nönõnõnõ †_Í €XH

0x1C12	0~4	RXPDO	R/W	UINT32	0~32767	1600	
0x1C13	0~2	TXPDO	R/W	UINT32	0~32767	1A00	
0x1C32	0~18	RXPDO	R	UINT	0~32767		
0x1C33	0~10	TXPDO	R	UINT	0~32767		

nýo³nyZáMDnõ ‘n÷nõnõnõ †_Í €XH

0x2000	0		R/W	UINT16	0~8100	1500	mA

nýo³nyÌZáMDnõ ‘nûnõnõnõ †_Í €XH5050

0x606C	0		R	DINT	-2,147,483,648~2,147,483,647	0	P/S
—							

0x607A	0		R/W	DINT	-2,147,483,648~2,147,483,647	0	P
—							

0x60FF	0		R/W	DINT	-2,147,483,648~2,147,483,647	0	P/S
pv	3						

0x607C	0		R/W	DINT	-2,147,483,648~2,147,483,647	0	P
—							

0x6080	0		R/W	UDINT	0~4,294,967,295	833333	—
—							

0x6081	0		R/W	UDINT	0~4,294,967,295	0	—
—							

0x609A	0		R/W	UDINT	0~4,294,967,295	833333	P/S^2

—

0x60B8	0		R/W	Uint16	0~65535	0	—

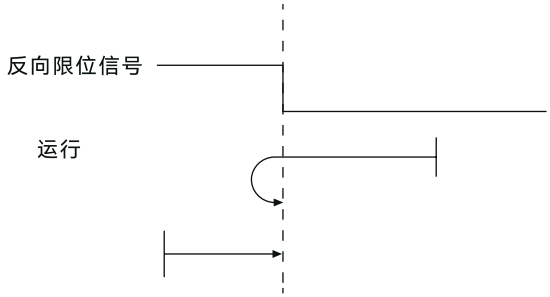
0x60B9	0		RO	U	0~65535	0	—

0x60BA	0	1					

l¬ nþ l` %^" 49-•

nþo³%ö" 49-•p(nönúHMp)

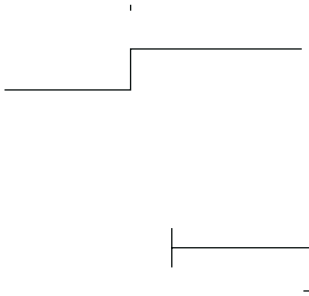
%^" 49-•nönüoâ e"M"‘dÐ Í a"w%^" p nûnõnþný p nönüp



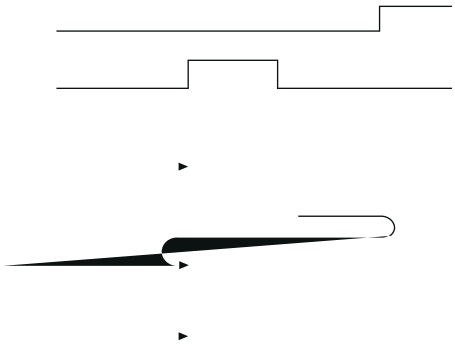
A:

B:

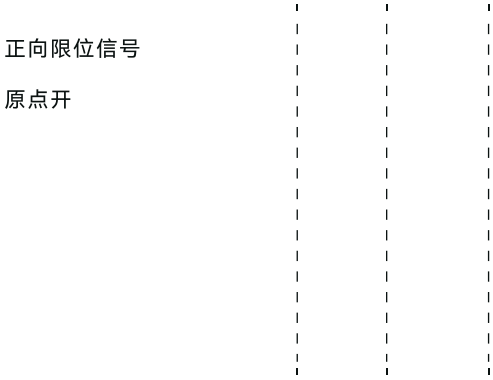
%^" 49-•n÷n÷oâ e" ?9 a"₩%^" p nûnõnþný p n÷n÷p ^PlÅÞ…ç• oµ"^" !ÝÂ*ò4voä" ?9-€ ó aRw4`3ÈoäC²5º e^



%^" 49-•n÷nùoâ e" ?9 a"w# 9ã"‘dĐ Í a"w %^" p nûnõnþný p n÷nùp



%^" 49-•n÷nûoâ e" ?9 a"w# 9ã"‘dĐ Í a"w %^" p nûnõnþný p n÷nûp



%^" 49-•n÷nýoâ e" ?9 a"w# "M"‘dĐ Í a"w %^" p nûnõnþný p n÷nýp

反向限位信号

原点

I¬ nönõ I3Åe '„B†

HCFA